

Exercise Sheet #05

Problem 1 (Grover's Algorithm with multiple marked elements)

$$O_f : |x\rangle \rightarrow (-1)^{f(x)} |x\rangle \quad f(x) = \begin{cases} 1 & \text{if } x = x_0 \\ 0 & \text{otherwise} \end{cases}$$

$$\Rightarrow O_f = \mathbb{1} - 2 \sum_{x, f(x)=1} |x\rangle \langle x|$$

$$|\alpha\rangle = \frac{1}{\sqrt{R}} \sum_{x, f(x)=1} |x\rangle, \quad |\beta\rangle = \frac{1}{\sqrt{N-R}} \sum_{x, f(x)=0} |x\rangle$$

$$|w\rangle = H^{\otimes n} |0\rangle^{\otimes n} = \frac{1}{\sqrt{N}} \sum_x |x\rangle = \sqrt{\frac{R}{N}} |\alpha\rangle + \sqrt{\frac{N-R}{N}} |\beta\rangle$$

$$\text{Let } \sin \varphi = \sqrt{\frac{R}{N}} \Rightarrow \cos \varphi = \sqrt{\frac{N-R}{N}}$$

$$\Rightarrow |w\rangle = \sin \varphi |\alpha\rangle + \cos \varphi |\beta\rangle$$

$$O_w = \mathbb{1} - 2 |w\rangle \langle w|$$

Algorithm.

Start from $|\psi_0\rangle = |w\rangle$ and apply Grover's iteration $G = (-O_w) O_f$.

$$|\psi_{k+1}\rangle = G |\psi_k\rangle$$

$$O_f |w\rangle = \left(\mathbb{1} - 2 \sum_{x, f(x)=1} |x\rangle \langle x| \right) (\sin \varphi |\alpha\rangle + \cos \varphi |\beta\rangle)$$

$$= -\sin \varphi |\alpha\rangle + \cos \varphi |\beta\rangle$$

$$|\psi_1\rangle = G |\psi_0\rangle = -O_w O_f |w\rangle = (2 |w\rangle \langle w| - \mathbb{1}) (-\sin \varphi |\alpha\rangle + \cos \varphi |\beta\rangle)$$

$$= 2 |w\rangle \underbrace{(-\sin^2 \varphi + \cos^2 \varphi)}_{\cos 2\varphi} + (\sin \varphi |\alpha\rangle - \cos \varphi |\beta\rangle)$$

$$= (\sin \varphi + 2 \sin \varphi \cos 2\varphi) |\alpha\rangle + (-\cos \varphi + 2 \cos \varphi \cos 2\varphi) |\beta\rangle$$

$$= \sin 3\ell |\alpha\rangle + \cos 3\ell |\beta\rangle$$

$$|4_1\rangle = \sin((2(1)+1)\ell) |\alpha\rangle + \cos((2(1)+1)\ell) |\beta\rangle$$

$$|4_k\rangle = \sin((2k+1)\ell) |\alpha\rangle + \cos((2k+1)\ell) |\beta\rangle$$

Measurement will give the result with probability 1,

$$\text{if } \sin^2((2k+1)\ell) = 1$$

$$\Rightarrow \sin((2k+1)\ell) = 1$$

$$\Rightarrow (2k+1)\ell = \pi/2$$

$$k = \pi/4\ell - 1/2$$

~~sin~~
$$\sin \ell = \sqrt{\frac{\lambda}{N}}$$

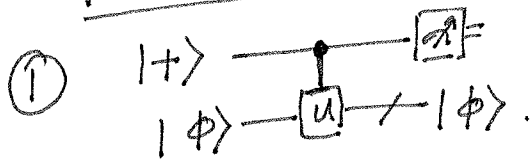
$$\text{But } \lambda \ll N$$

$$\Rightarrow \ell \approx \sqrt{\frac{\lambda}{N}}$$

$$\Rightarrow k \approx \frac{\pi}{4} \sqrt{\frac{N}{\lambda}} - \frac{1}{2} \approx \left\lceil \frac{\pi}{4} \sqrt{\frac{N}{\lambda}} \right\rceil$$

Problem # 02

Phase Estimation



$$|+\rangle|\phi\rangle = \frac{|0\rangle + |1\rangle}{\sqrt{2}}|\phi\rangle \xrightarrow{CU} \left(\frac{|0\rangle + e^{2\pi i \phi} |1\rangle}{\sqrt{2}} \right) |\phi\rangle$$

$$P_+ = \frac{\langle + | (|0\rangle + e^{2\pi i \phi} |1\rangle) \rangle^2}{2}$$

$$P_+ = \frac{|1 + e^{2\pi i \phi}|^2}{4} = \frac{2 \cos 2\pi \phi + 2}{4}$$

$$P_+ = \cos^2 \pi \phi$$

$$\sqrt{N} \left| \frac{n_+}{N} - P_+ \right| \xrightarrow[\text{Normality}]{\text{Asymptotic}} \mathcal{N}(0, \sigma^2)$$

$$\Rightarrow \sqrt{N} \left| \frac{n_+}{N} - P_+ \right| \leq c \sigma$$

$$\text{err} = \left| \frac{n_+}{N} - P_+ \right| \leq \frac{c \sigma}{\sqrt{N}}$$

$$\text{acc} = -\log(\text{err})$$

$$\geq -\log\left(\frac{c \sigma}{\sqrt{N}}\right) = -\log(c \sigma^2) + \log(\sqrt{N})$$

N is exponential in accuracy.

② a) $CU_{n-1} \equiv \text{Cont-}U^{(2^{n-1})}$

$$|+\rangle|\phi\rangle = \frac{1}{\sqrt{2}}(|0\rangle + |1\rangle)|\phi\rangle \xrightarrow{CU_{n-1}} \frac{1}{\sqrt{2}}(|0\rangle + e^{2\pi i \phi 2^{n-1}} |1\rangle)|\phi\rangle$$

$$= \frac{1}{\sqrt{2}}(|0\rangle + e^{2\pi i (0 \cdot \phi_1 \phi_2 \dots \phi_n) 2^{n-1}} |1\rangle)|\phi\rangle$$

$$= \frac{1}{\sqrt{2}}(|0\rangle + e^{2\pi i \phi_1 \phi_2 \dots \phi_{n-1} + 2\pi i 0 \cdot \phi_n} |1\rangle)|\phi\rangle$$

$$= \frac{1}{\sqrt{2}} (|0\rangle + e^{2\pi i 0 \cdot \phi_n} |1\rangle) |\phi\rangle$$

$$e^{2\pi i 0 \cdot \phi_n} = 1 \text{ when } \phi_n = 0$$

$$e^{2\pi i 1 \cdot \phi_n} = -1 \text{ when } \phi_n = 1.$$

⇒ measurement outcome '+' ⇒ $\phi_n = 0$
 '−' ⇒ $\phi_n = 1$

determines ϕ_n exactly

$$\textcircled{b} CU_{n-2} |+\rangle |\phi\rangle = \frac{1}{\sqrt{2}} (|0\rangle + e^{2\pi i (0 \cdot \phi_1 \phi_2 \dots \phi_n) 2^{n-2}} |1\rangle) |\phi\rangle$$

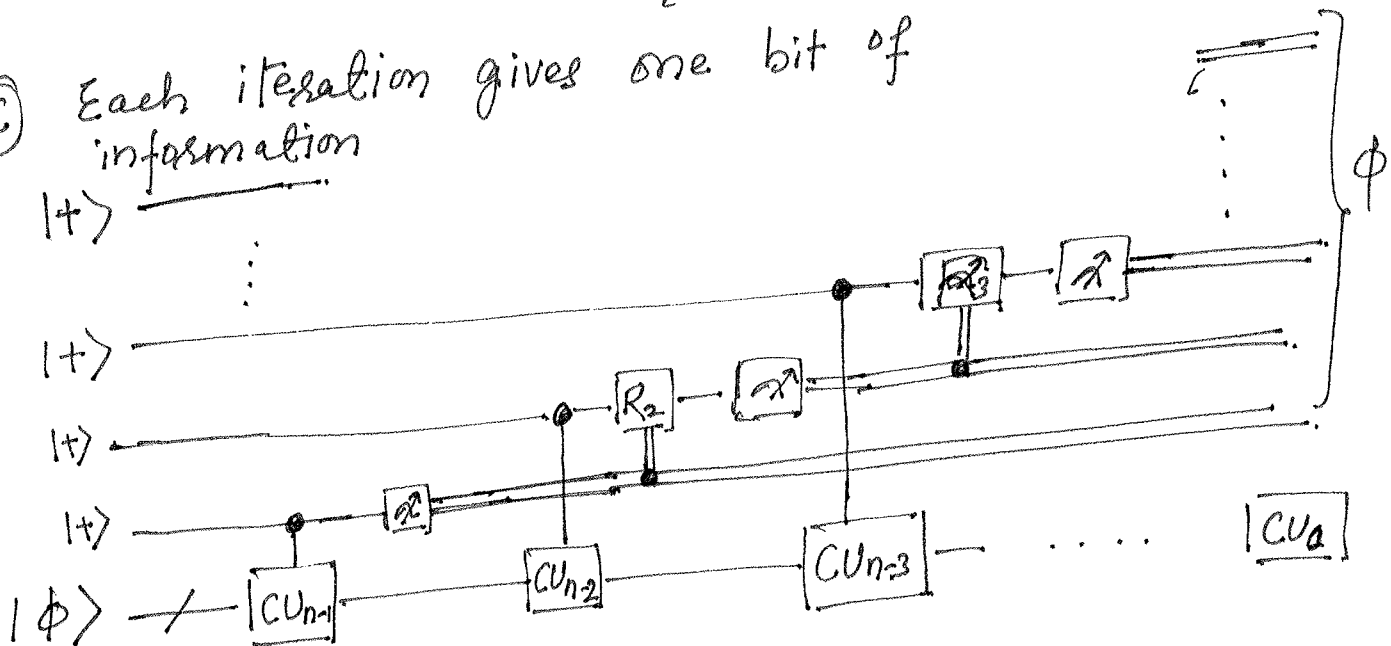
$$= \frac{1}{\sqrt{2}} (|0\rangle + e^{2\pi i \phi_{n-1}} e^{2\pi i \phi_n / 4} |1\rangle) |\phi\rangle.$$

Let $R_k = \begin{pmatrix} 1 & \\ & e^{-2\pi i / 2^k} \end{pmatrix}$

$$\xrightarrow{CR_2^{\otimes 2}} \frac{1}{\sqrt{2}} (|0\rangle + e^{2\pi i \phi_{n-1}} |1\rangle) |\phi\rangle$$

Measurement outcome '+' ⇒ $\phi_{n-1} = 0$
 '−' ⇒ $\phi_{n-1} = 1$.

Each iteration gives one bit of information

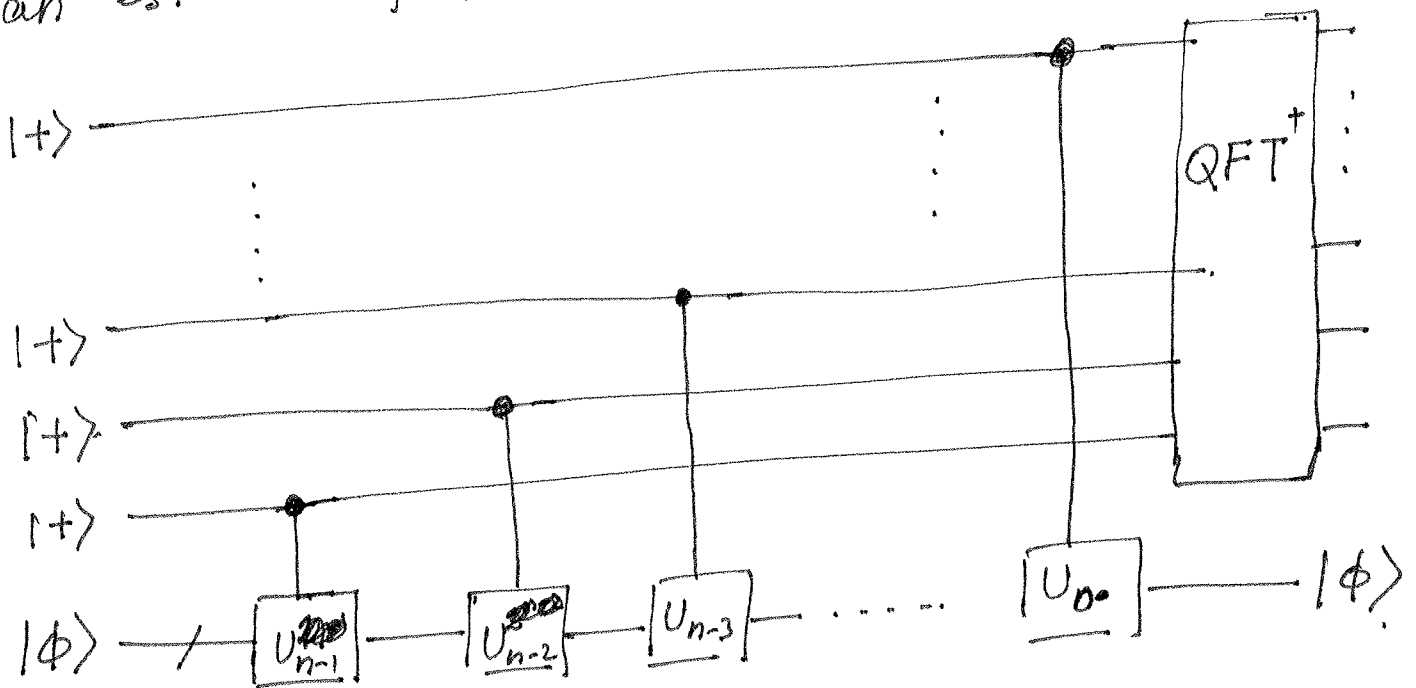


* U^{2^k} must be applied n times for each value of k between 1 and N

$$\begin{aligned}
 \textcircled{3} \quad \sum_{\alpha} |\alpha\rangle |\phi\rangle &\xrightarrow{U\text{-transform}} \sum_{\alpha} |\alpha\rangle U^{\alpha} |\phi\rangle \\
 &= \sum_{\alpha} |\alpha\rangle e^{2\pi i \alpha \cdot 0 \cdot \phi_1 \phi_2 \dots \phi_n} |\phi\rangle \\
 &= \sum_{\alpha} e^{2\pi i \alpha \cdot (\phi_1 \phi_2 \dots \phi_n) / 2^n} |\alpha\rangle |\phi\rangle
 \end{aligned}$$

$$\xrightarrow{FT_n^+ \otimes I} |\phi_1 \phi_2 \dots \phi_n\rangle |\phi\rangle$$

Measurement on first register gives an estimate of ϕ with n -bits of accuracy.



U^{2^k} has to be applied n -times for different values of k .

$\textcircled{4}$ Fourier transform = One qubit gate + measurement + Classical control

$$\textcircled{5} |++\dots+\rangle|c\rangle \xrightarrow[\text{Estimation}]{\text{Phase}} |c_1 c_2 \dots c_n\rangle|c\rangle$$

$$\Rightarrow \sum_k w_k |++\dots+\rangle|c_k\rangle \xrightarrow[\text{Estimation}]{\text{Phase}} \sum_k w_k |c_1^k c_2^k \dots c_n^k\rangle|c_k\rangle$$

$$\textcircled{6} U: |x\rangle \longrightarrow |ax \pmod N\rangle$$

$$\text{Eigenvalues of } U = \left\{ e^{2\pi i k/r} \mid k=0,1,\dots,r-1 \right\}$$

$$|++\dots+\rangle|x^k\rangle \xrightarrow[\text{Estimation}]{\text{Phase}} |x_1^k x_2^k \dots x_n^k\rangle|x^k\rangle$$

$(x_1^k x_2^k \dots x_n^k)$ gives a binary representation of x^k/r with an accuracy of n bits

$\textcircled{7}$ If $|x^k\rangle = \frac{1}{\sqrt{r}} \sum_{l=0}^{r-1} e(-2\pi i l k/r) |a^l \pmod N\rangle$ then $|x^k\rangle$ is an eigenvector of U with eigenvalue $e(2\pi i k/r)$

$$\frac{1}{\sqrt{r}} \sum_k |x^k\rangle = \frac{1}{r} \sum_{k=0}^{r-1} \sum_{l=0}^{r-1} e(-2\pi i k l/r) |a^l \pmod N\rangle$$

$$= \frac{1}{r} \sum_{l=0}^{r-1} \underbrace{\left(\sum_{k=0}^{r-1} e\left(-2\pi i \frac{l}{r} k\right) \right)}_{r \delta_{0l}} |a^l \pmod N\rangle$$

$$= \frac{1}{r} \sum_{l=0}^{r-1} r \delta_{0l} |a^l \pmod N\rangle$$

$$= |1\rangle$$

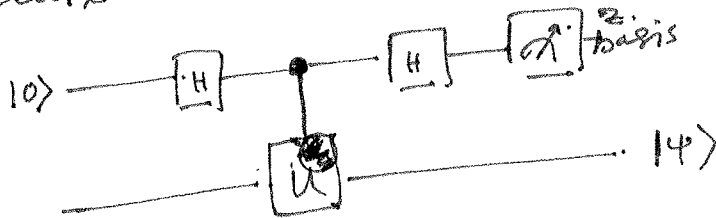
$$|++\dots+\rangle|1\rangle \xrightarrow[\text{Estimation}]{\text{Phase}} \frac{1}{\sqrt{r}} \sum_{k=0}^{r-1} |c_1^k c_2^k \dots c_n^k\rangle|c_k\rangle$$

Each measurement outcome give an estimate of x/r up to n -bit accuracy. From k/r one can obtain x using continued fraction.

Problem #03 (Syndrome Measurement and Correction for Stabilizer Codes)

① 3-qubit flipcode.

(a,b) Given a unitary U , with eigenvalues $\{1, -1\}$ and eigenvectors $\{|u_+\rangle, |u_-\rangle\}$, one can do a measurement in u . basis with the following circuit



$$\alpha|u_+\rangle + b|u_-\rangle$$

$$(|0\rangle + |1\rangle)(\alpha|u_+\rangle + b|u_-\rangle) \xrightarrow{CU} |0\rangle(\alpha|u_+\rangle + b|u_-\rangle) + |1\rangle(\alpha|u_+\rangle - b|u_-\rangle)$$

$$\xrightarrow{H \otimes I} \frac{(|0\rangle + |1\rangle)}{\sqrt{2}}(\alpha|u_+\rangle + b|u_-\rangle) + \frac{(|0\rangle - |1\rangle)}{\sqrt{2}}(\alpha|u_+\rangle - b|u_-\rangle)$$

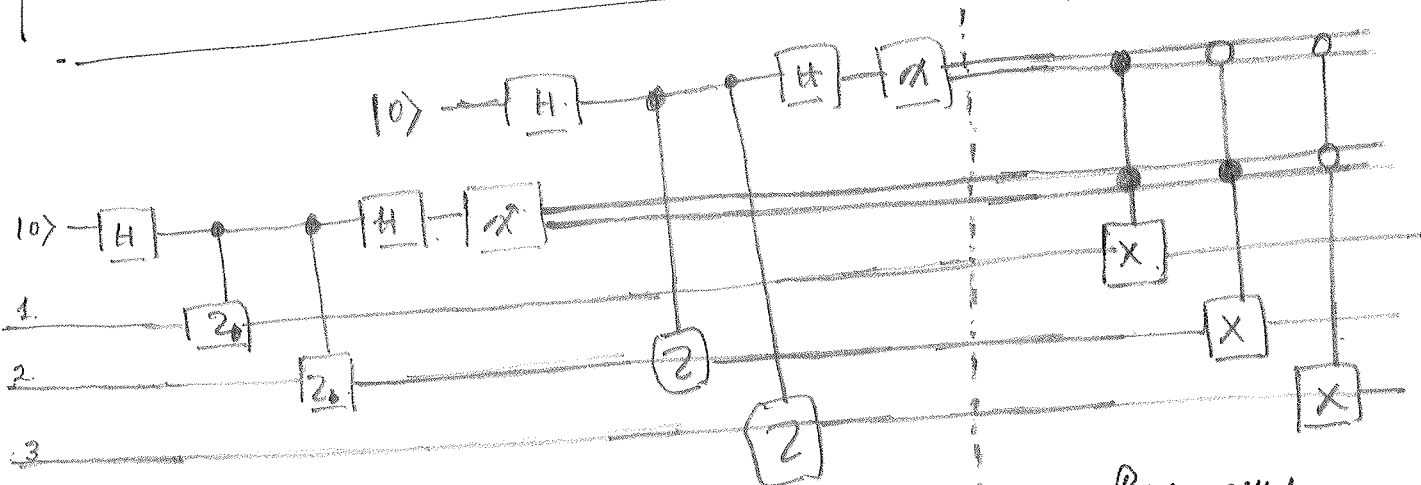
$$= \alpha|0\rangle|u_+\rangle + b|1\rangle|u_-\rangle$$

If the outcome is:

$$"0" \quad |u\rangle = |u_+\rangle$$

$$"1" \quad |u\rangle = |u_-\rangle$$

Circuit implements a POVM. $\mathcal{K} = \{|u_+\rangle\langle u_+|, |u_-\rangle\langle u_-|\}$.



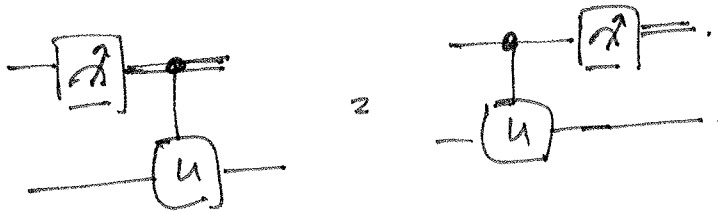
Syndrome measurement

Recovery.

Receiver	Error	$S_1 = Z_1 Z_2$	$S_2 = Z_2 Z_3$	Recovery
$a 000\rangle + b 111\rangle$	I.	0	0	I.
$a 001\rangle + b 110\rangle$	X_3	0	1	X_3
$a 010\rangle + b 101\rangle$	X_2	1	1	X_2
$a 100\rangle + b 011\rangle$	X_1	1	0	X_1

- * Syndrome is 0 if error commutes with the stabilizer S_i
- * Syndrome is 1 if error anticommutes with the stabilizer S_i

(c) This can be achieved by deferred Measurement Principle.

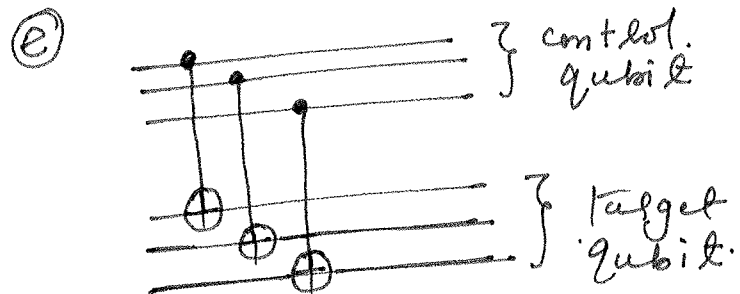


(d)

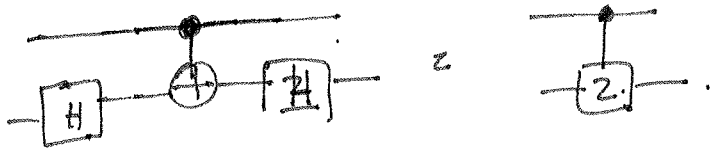
$$\bar{X} = XXX$$

$$\bar{Z} = ZZZ$$

$$\bar{Y} = YYY$$



② Syndrome measurement and error correction can be performed by Pauli's and measurement in Z-basis.



③ Five qubit code.

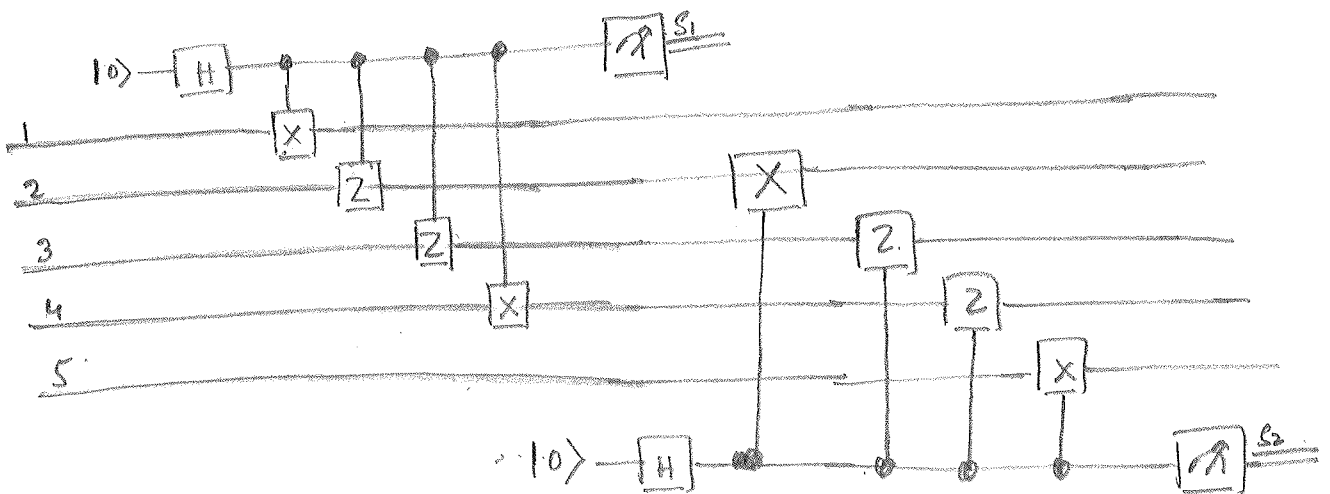
Stabilizers for 5-qubit Steane code

$$S_1 = XZIZXI$$

$$S_2 = IXZZX$$

$$S_3 = XIZZZ$$

$$S_4 = ZXIZXZ$$



First two syndrome measurements.

4)

errors	$S_1 = XZ2XI$	$S_2 = IXZ2X$	$S_3 = XIXZ2$	$S_4 = ZXIX2$
X_1	0	0	0	1
X_2	1	0	0	0
X_3	1	1	0	0
X_4	0	1	1	0
X_5	0	0	1	1
Y_1	1	0	1	1
Y_2	1	1	0	1
Y_3	1	1	1	0
Y_4	1	1	1	1
Y_5	0	1	1	1
Z_1	1	0	1	0
Z_2	0	1	0	1
Z_3	0	0	1	0
Z_4	1	0	0	1
Z_5	0	1	0	0
I	0	0	0	0

Each error has unique Syndrome
 The code is non-degenerate.